

<b>COURSE NUMBER</b>	<b>ME 455</b>		
<b>COURSE TITLE</b>	<b>Introduction to Automatic Controls</b>		
<b>COURSE STRUCTURE</b>	(3-0-3) (lecture hr/wk - lab hr/wk – course credits)		
<b>COURSE COORDINATOR</b>	Z. Ji		
<b>COURSE DESCRIPTION</b>	Introduction to modern control methods applied to mechanical, manufacturing, and mechatronic systems.		
<b>PREREQUISITE(S)</b>	ME 305 – System Dynamics		
<b>COREQUISITE(S)</b>	None		
<b>REQUIRED, ELECTIVE OR SELECTED ELECTIVE</b>	Elective		
<b>REQUIRED MATERIALS</b>	<ol style="list-style-type: none"> <li>1. Modern Control Systems (12th Edition), by Richard C. Dorf and Robert H. Bishop, Prentice Hall, 2011, ISBN 0136024580</li> <li>2. MATLAB with Control Toolbox</li> </ol>		
<b>Other supplemental materials (not Required)</b>	None		
<b>COMPUTER USAGE</b>	MATLAB software with Control Toolbox		
<b>COURSE LEARNING OUTCOMES/ EXPECTED PERFORMANCE CRITERIA:</b>	Course Learning Outcomes	SOs*	Expected Performance Criteria
	1. model dynamic systems through block diagrams and signal flow graphs.	a, e, k	Exam Question (80% of the students will earn a grade of 70% or better on this question)
	2. understand state variable models of feedback control systems	a, e, k	Exam Question (80% of the students will earn a grade of 70% or better on this question)
	3. analyze characteristics of dynamics systems and measures of their performances	a, e, k	Exam Question (80% of the students will earn a grade of 70% or better on this question)
	4. analyze and assess system stability	a, e, k	Exam Question (80% of the students will earn a grade of 70% or better on this question)
	5. perform root locus analysis	a, e, k	Exam Question (80% of the students will earn a grade of 70% or better on this question)
	6. use MATLAB in analyzing	a, e, k	Homework Problems

	dynamics systems and control systems		(80% of the students will earn a grade of 80% or better on these problems)								
<b>CLASS TOPICS</b>	<ol style="list-style-type: none"> <li>1. Introduction; MATLAB Basics</li> <li>2. Block Diagram, Signal Flow Graph and Transfer Function</li> <li>3. State Variable Models</li> <li>4. Control System Characteristics</li> <li>5. Measures of Performance</li> <li>6. Stability: Routh–Hurwitz method</li> <li>7. Root Locus Method</li> <li>8. Frequency Response: Bode Diagrams</li> <li>9. Stability: Nyquist Criterion</li> </ol>										
<b>STUDENT OUTCOMES (SCALE: 1-3)</b>	a	b	c	d	e	f	g	h	i	j	k
	3				2						2
	3 – Strongly supported      2 – Supported 1 – Minimally supported										

\* Student Outcomes